

# Anisotropic curvature flow as singular limit of the bidomain model

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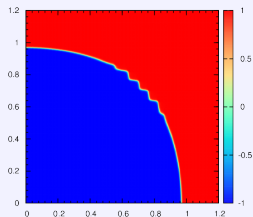
Università Cattolica di Brescia

Padova, april 2012

numerical simulations by **Franco Pasquarelli**, based on code by **Meggie Bugatti**, Università Cattolica di Brescia

# Outline of the talk

- The Allen-Cahn equation
- Anisotropy and anisotropic Allen-Cahn
- The **bidomain** system
- Historical remarks
- Combined anisotropy and nonconvexity
- Numerical simulations in 2D

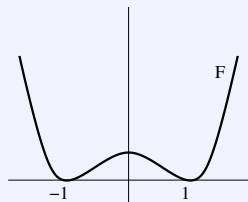


# Allen-Cahn equation: brief review

Reaction/diffusion equation arising in the context of **phase transitions** with a diffused interface:

$$\begin{cases} \varepsilon \partial_t u - \varepsilon \Delta u + \frac{1}{\varepsilon} f(u) = 0 & \text{in } \Omega \\ + \text{ initial and boundary conditions} \end{cases}$$

- $u$ : order parameter (phase indicator),
- $\Omega$ : domain in  $\mathbb{R}^d$ ,  $d = 2, 3$ ,
- $\varepsilon > 0$ : small relaxation parameter,
- $f = F'$ : derivative of a double equal well potential  $F$  (or double-obstacle: deep quench limit [Elliott et al]).



The solution  $u$  exhibits a thin transition layer  $\mathcal{O}(\varepsilon)$ -wide between the phase  $u \approx -1$  and the phase  $u \approx +1$ .

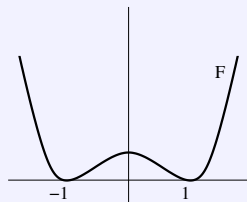
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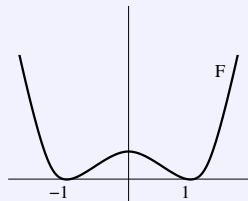
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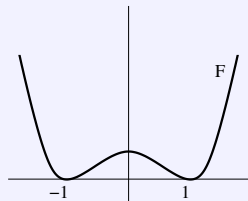
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$$V = -\kappa$$

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Optimal  $\mathcal{O}(\varepsilon^2)$  or quasi-optimal  $\mathcal{O}(\varepsilon^2 |\log \varepsilon|)$  error estimate.

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Described by a norm  $\varphi : \mathbb{R}^d \rightarrow \mathbb{R}$ :

- $\varphi(\xi) \geq 0 \quad \forall \xi \in \mathbb{R}^d; \varphi(\xi) = 0 \iff \xi = 0$ ;
- $\varphi(t\xi) = t\varphi(\xi) \quad \forall t \geq 0$ ;
- $\varphi(\xi + \eta) \leq \varphi(\xi) + \varphi(\eta)$ .

Dual norm:  $\varphi^\circ(\xi^*) = \max_{\varphi(\xi) \leq 1} \xi \cdot \xi^*$ .

Duality map (nonlinear, monotone, homogeneous of degree one):

$$T(\xi) = \frac{1}{2} \nabla_{\xi} [\varphi^\circ(\xi)]^2$$

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# Anisotropy (2)

Wulff shape:  $W_\varphi = \{\varphi(\xi) \leq 1\}$ ;

Frank diagram:  $F_\varphi = \{\varphi^\circ(\xi) \leq 1\}$ ;

$$T : F_\varphi \rightarrow W_\varphi$$

Linear anisotropy

$$[\varphi^\circ(\xi)]^2 = \xi^T A \xi, \quad A \text{ symmetric positive definite.}$$

So that  $[\varphi(\xi)]^2 = \xi^T A^{-1} \xi$  and  $T(\xi) = A\xi$ .

Strictly convex anisotropy

Both  $\varphi$  and  $\varphi^\circ$  strictly convex.

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[Taylor, Bellettini-Novaga-P.,...]

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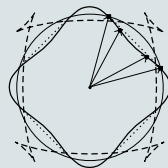
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## Nonconvex anisotropy

$F_\varphi$  is not convex: illposedness



[Fierro-Gogliione-P.,...]



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Singular limit  $\varepsilon \rightarrow 0$

Geometric evolution  $V \cdot \nu_\varphi = -\kappa_\varphi$ ;  $\kappa_\varphi = \operatorname{div} n_\varphi$ ;

Cahn-Hoffman vector:  $n_\varphi = T(\nu_\varphi)$ ;  $\nu_\varphi = \frac{\nu}{\varphi^\circ(\nu)}$

[Elliott-Schätzle-P, Bellettini-Colli Franzone-P.]  
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# The bidomain system

The bidomain model is a singularly perturbed degenerate system of two reaction–diffusion equations in the unknowns  $u_1$  and  $u_2 : \Omega \rightarrow \mathbb{R}$ :

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in  $\Omega \in \mathbb{R}^d$  with appropriate initial and boundary conditions.  $T_{1,2}$  are the duality mappings of two strictly convex anisotropies  $\varphi_{1,2}$ ,  $f = F'$  is the derivative of the quartic double-well potential  $F(s) = (s^2 - 1)^2$ ,  $\varepsilon > 0$  is a small relaxation parameter. It can be generalized to more components  $u_1, \dots, u_m$ .

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# Origin: electric model for the myocardium

[Colli Franzone, ...]

- Simulation of a complete heart-beat, but specifically of the depolarization phase;
- starting from a microscopic model of the electrical properties of the (disjoint) intracellular and extracellular media  $\Omega^i$  and  $\Omega^e$  in the cardiac tissue
- coupled through the cellular membrane;
- with the addition of a number of “gating variables” (Hodgkin–Huxley model), simplified to a single “recovery variable” (FitzHugh–Nagumo);
- the recovery variable (which we shall neglect) allows to recover the rest state of the cell (repolarization);
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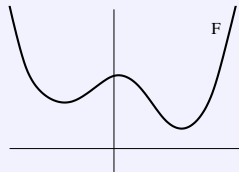
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$$u_1 = u^i; \quad u_2 = -u^e$$

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- Cells form elongated fibers with orientation that depends strongly on position, and this geometry is the source of the anisotropy;
- $M^i, M^e$ : symmetric positive definite matrices modelling the anisotropy induced by the cell orientations.

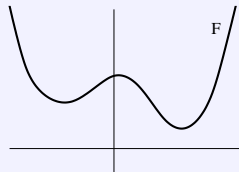
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Remarks on the bidomain model:

- 1 the two local minima of  $F$  are different;
  - 2 rescaled time:  $\partial_t u$  instead of  $\varepsilon \partial_t (u_1 + u_2)$ ;
  - 3 presence of a (pointwise) recovery variable;
  - 4 space dependant anisotropy  $M^{i,e} = M^{i,e}(x)$  (Finsler metric).
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# The anisotropy in the bidomain model

Recall:

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Matrices  $M^i$  and  $M^e$  (in general depending on position) are symmetric positive definite with common eigenvectors consistent with fiber orientation. The eigenvalues  $\lambda_k^i, \lambda_k^e, k = 1, 2, 3$  come from the homogenization procedure of the microscopic geometry and depend on properties of the intra and extra-cellular media.

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Special case  $M^e = \rho M^i$  (equal anisotropic ratio) the system reduces to a single reaction-diffusion Allen-Cahn equation for  $u = u^i - u^e$

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## Remark

We can substitute one of the two parabolic equations with the elliptic combination

$$\operatorname{div} T_1(\nabla u_1) = \operatorname{div} T_2(\nabla u_2) \quad \text{in } \Omega.$$

The bidomain model is a degenerate parabolic system.

$$\mathbf{u} = [u_1, u_2]^T, \quad \mathbf{q} = [T_1(\nabla u_1), T_2(\nabla u_2)]^T$$

$$\varepsilon \partial_t (B\mathbf{u}) - \varepsilon \operatorname{div} \mathbf{q} + \frac{1}{\varepsilon} \mathbf{f}(\mathbf{u}) = 0$$

where

- $B = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$  (singular!);
- $\operatorname{div}$  acts componentwise
- $\mathbf{f}(\mathbf{u}) = [f(u_1 + u_2), f(u_1 + u_2)]^T$

Although matrix  $B$  is singular the problem is well-posed, at least for linear anisotropies  $T_i(\xi) = A_i \xi$  and any choice of two symmetric positive-definite matrices  $A_1, A_2$ .

[Colli Franzone-Savaré]



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# The combined anisotropy

For convenience we introduce  $\alpha_i(\xi) = [\varphi_i^\circ(\xi)]^2$ ,  $i = 1, 2$ .  
(For the bidomain model they are  $\alpha^{i,e} = \xi^T M^{i,e} \xi$ .)

The *combined* value  $\alpha$  is their **harmonic mean**:

$$\alpha = \frac{\alpha_1 \alpha_2}{\alpha_1 + \alpha_2}$$

The **combined anisotropy** is defined as

$$\varphi^\circ(\xi) = \sqrt{\alpha} = \sqrt{\frac{\alpha_1 \alpha_2}{\alpha_1 + \alpha_2}}$$

## Remarks

- 1 Linear anisotropies generally produce a **nonlinear** combined anisotropy;
- 2 Strictly convex anisotropies (even linear) can produce a **nonconvex** combined anisotropy (using  $\varphi^\circ$  is an abuse of notation in this case).

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The **combined anisotropy** is defined as

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- 2 Strictly convex anisotropies (even linear) can produce a **nonconvex** combined anisotropy (using  $\varphi^\circ$  is an abuse of notation in this case).

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where  $\varphi$  denotes the (dual of the) combined anisotropy.

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$\varphi^\circ$  is not guaranteed to be convex. If it is, then it is a norm and we have anisotropic curvature flow.

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[Bellettini-Colli Franzone-P.]
- 2  $\Gamma$ -convergence result for the stationary bidomain system, consistent with the formal asymptotics, but without a complete identification of the  $\Gamma$ -limit.  
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# Gamma-limit of the stationary problem

[L. Ambrosio, P. Colli Franzone, G. Savaré ('00)]

In the linear case ( $\alpha_i$  are quadratic forms), the functional

$$\mathcal{F}_\varepsilon(\mathbf{u}) = \varepsilon \int_{\Omega} [\alpha_1(\nabla u_1) + \alpha_2(\nabla u_2)] dx + \frac{1}{\varepsilon} \int_{\Omega} F(u_1 + u_2) dx$$

where  $\mathbf{u} = [u_1, u_2]^T$ ,  $\Gamma$ -converges (in the  $L^2$  topology) to a limit functional

$$\mathcal{F}(\mathbf{u}) = \int_{S_u^*} \phi(\nu(x)) d\mathcal{H}^{d-1}(x)$$

that depends only in the sum  $u = u_1 + u_2$  which is a  $BV$  function taking values in  $\{-1, 1\}$  with  $S_u^*$  as its jump set and  $\nu(x)$  the corresponding unit normal.

# Identification of $\phi$

Although the formal asymptotics suggests that

$$\phi(\xi) = c_0 \varphi^o(\xi) = c_0 \sqrt{\frac{\alpha_1 \alpha_2}{\alpha_1 + \alpha_2}}$$

with  $c_0$  depending on the specific shape of  $F$ , the actual value on  $\phi$  is not known yet. [Ambrosio et al] proved the following estimates

$$\underline{\phi}(\xi) \leq \phi(\xi) \leq c_0 \varphi^o(\xi)$$

with (setting  $\alpha_i(\xi) = \xi^T A_i \xi$ ,  $A_i$  symmetric positive definite)

$$\underline{\phi}(\xi) = \sqrt{\xi^T A_1 (A_1 + A_2)^{-1} A_2 \xi}$$

## Inverted anisotropic ratio, $d = 2$

We make a linear choice for the anisotropy:

$$[\varphi_i^o(\xi)]^2 = \xi^T A_i \xi, \quad T_i(\xi) = A_i \xi, \quad i = 1, 2.$$

For  $\rho \geq 1$  we choose diagonal matrices  $A_1, A_2$  as (inverted anisotropic ratio):

$$A_1 = \begin{bmatrix} 1 & 0 \\ 0 & \rho \end{bmatrix}, \quad A_2 := \begin{bmatrix} \rho & 0 \\ 0 & 1 \end{bmatrix}.$$

This choice is not physiologically feasible for the bidomain model of the heart tissue, however it leads to a nonconvex combined anisotropy if  $\rho > 3$ .

Might correspond to a pathological situation.

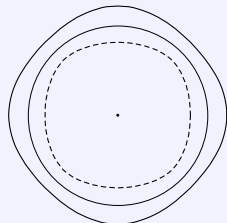
# Numerical simulations. Two choices for $\rho$

Weak inverted ratio

$\rho = 2$  (convex anisotropy)

Solid line: Frank diagram  $\{\varphi^\circ(\xi) = 1\}$ .

Dashed line: Wulff shape (dual shape).



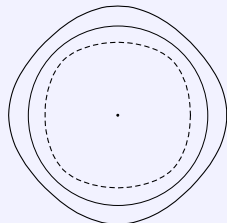


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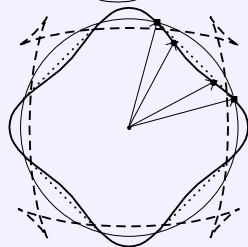
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## Strong inverted ratio

$\rho = 5$  (nonconvex anisotropy)

Convexification of Frank diagram corresponds to cutting off the swallowtails in the Wulff shape.



# Numerical simulations

In all simulations we chose a square domain  $\Omega = (0, 1.2) \times (0, 1.2)$ . The initial condition is such that  $u_1 + u_2 = \tanh \frac{\tilde{\varphi}(x)}{\epsilon}$  for some appropriate choice of a norm  $\tilde{\varphi}$ .

The relaxation parameter  $\epsilon$  related to space discretization  $h$  through  $h = C\epsilon$  ( $C$  small enough to resolve the transition layer). Reflection conditions along the axes and Dirichet condition on the other two sides.

Matrices  $A_1$ ,  $A_2$  are fixed according to the choice of weak or strong inverted ratio.

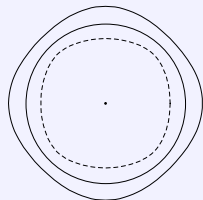
- We use  $P_1$  finite elements in space.
- The first parabolic equations is discretized with explicit Euler in time to get the sum  $u_1^{(n+1)} + u_2^{(n+1)}$  at the next time step.
- Then we recover  $u_1^{(n+1)}$  and  $u_2^{(n+1)}$  by solving an elliptic problem with a preconditioned conjugate gradient.

# Weak inverted anisotropic ratio

By choosing  $\rho = 2$  we obtain a convex combined anisotropy.

Solid line: Frank diagram

Dashed line: Wulff shape



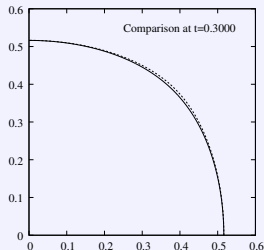
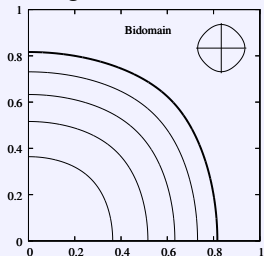
## Evolving the Wulff shape

The Wulff shape evolves selfsimilarly by anisotropic mean curvature

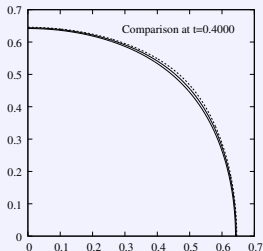
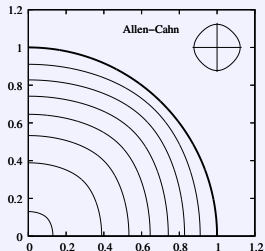
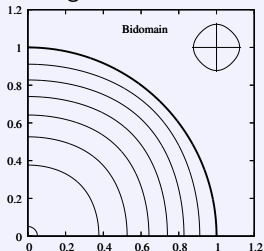
In all pictures we plot the zero-level curve of  $u_1 + u_2$  at different time steps.

# Simulations with $\rho = 2$

Starting from the Wulff shape,  $\varepsilon = 0.04$ ,  $h = 0.005$ , time intervals of 0.1:



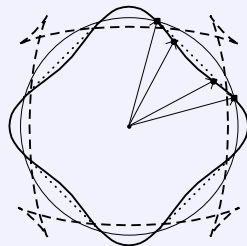
Starting from the unit circle,  $\varepsilon = 0.08$ ,  $h = 0.01$ , bidomain vs Allen-Cahn:



# Strong inverted anisotropic ratio

By choosing  $\rho = 5$  we obtain a nonconvex combined anisotropy.

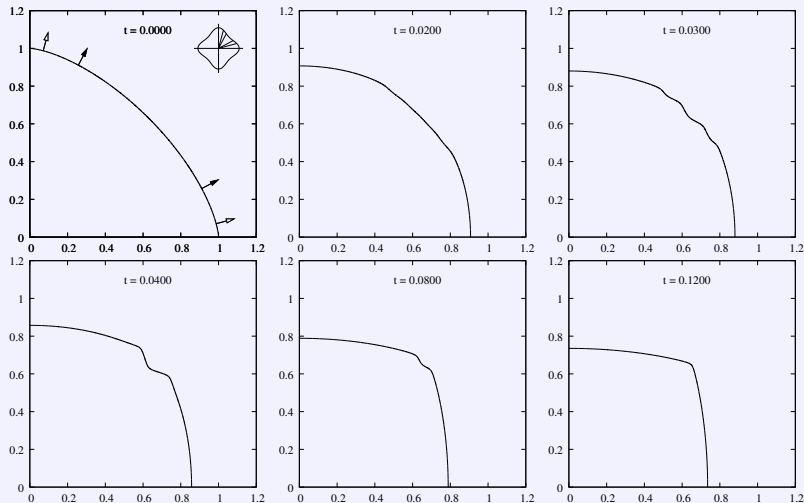
Solid line: Frank diagram  
Dashed line: Wulff shape



Interest in the evolution of those portions of the evolving front where the normal points in the nonconvex parts of the Frank diagram.

# Simulation with $\rho = 5$

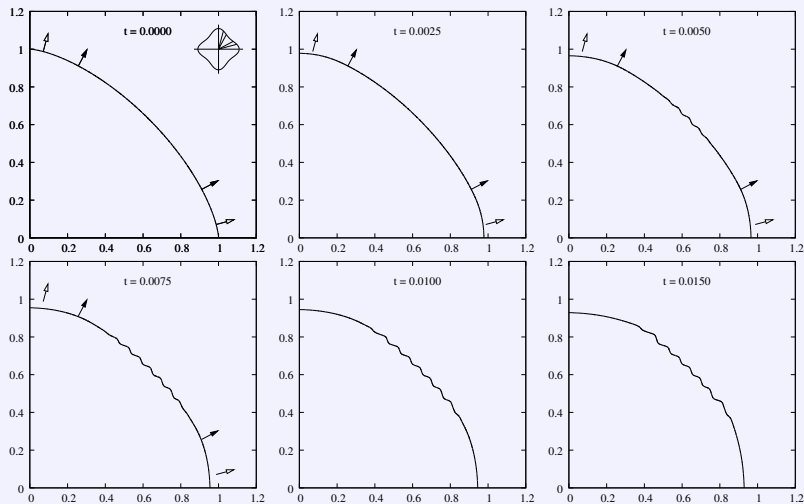
Starting from  $p = 1.5$  unit ball,  $\varepsilon = 0.008$ ,  $h = 0.002$ :



[see animation.avi]

# Simulation with $\rho = 5$ $\varepsilon = 0.004$

$\varepsilon = 0.004$ ,  $h = 0.002$ :

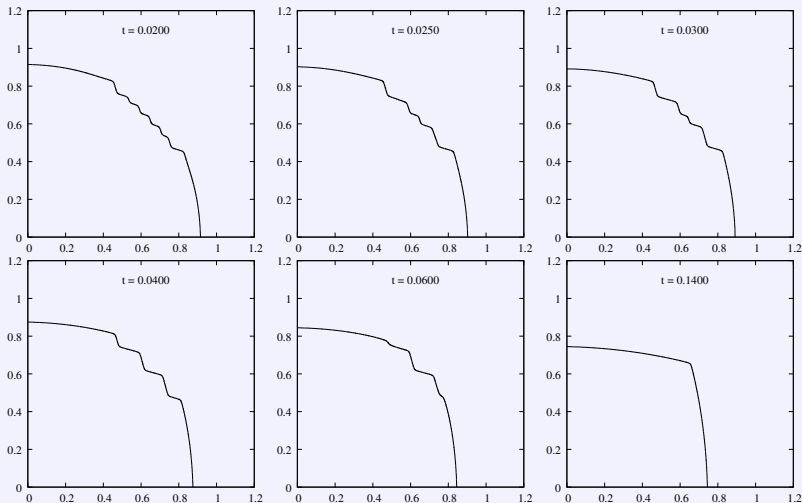


[see animation2.avi]



# Simulation with $\rho = 5$ $\varepsilon = 0.004$ (2)

Subsequent times...



[see animation2.avi]

# The wrinkling phenomenon and conclusions

- What we observe numerically (formation of wrinkles) is somewhat typical of an illposed evolution problem formally arising as gradient flow for an energy that is not convex when relaxed with the addition of a small higher order perturbation, or due to the discretization.
- The question is whether or not there is a “natural” way to describe the evolution in the singular limit  $\varepsilon \rightarrow 0$  (or  $h \rightarrow 0$ ).
- Surprisingly it seems that in most cases the limit **is not** the gradient flow by the **convexified energy**.
- This is not easily seen for the bidomain system due to the large wrinkles that arise even for quite small values of  $\varepsilon$ .